Motion Cyclification by Time x Frequency Warping

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Presentation Outline

- Motion Processing
- Motion Re-timing
- Human Motion Cyclification
- Our Motivation
- Time x Frequency Warping of 1D Signals
- Cyclification of Articulated Figure Motion
- Video / Conclusions / Future Work

Motion Processing

• Modification and reuse of animation parameters

• Examples

- kinematic and dynamic parameters.
- motion capture data.



- signal processing techniques.

Captured Data Processing

Motion curves: positional and rotational values

- sampling at joints of a real subject.

• Current techniques

- filtering, transition, warping, blending.

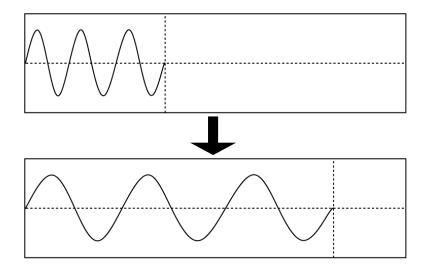
- Motion re-timing
 - changes duration of motion (in time).
 - main applications: games, facial animation, ...

Motion Re-timing

• Two different approaches

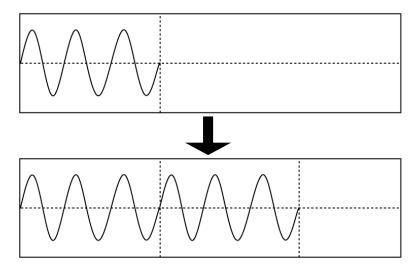
- reparametrization

- local resampling of motion curves ⇒ warping in time domain [Silva et al.98].
- frequency components are deformed ⇒ slow-motion and accelerated-time effects.



- cyclification

- detection and replication of motion cycles.
- current methods require user interaction and work well only for perfectly periodic motions.

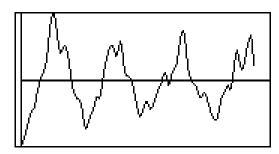


Human Motion Cyclification

- Motion curves have a complex structure
 - *shape*: basic motion patterns (low frequencies).
 - *texture*: subtleties, detail and noise (high frequencies).

• Captured motion curves are not perfectly periodic

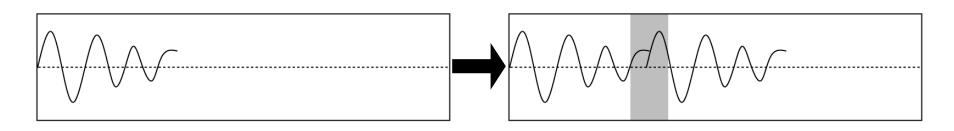
- biomechanic and external factors introduce a noise component fundamental to natural-looking motion [Perlin95].
- we call this class of motion as near-periodic.



motion captured joint curve (near-periodic signal)

Detection of Motion Cycles

- Complicated analysis for *near-periodic* motions
 - requires user interaction [Cohen et al.96].
 - not suitable for real-time applications.
- Boundary discontinuity
 - happens during the transition between motion cycles.
 - smoothing methods are required [Sudarsky98].



Our Motivation

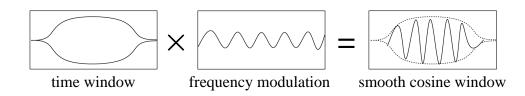
Develop an automatic method for periodic and near-periodic motion cyclification

• Our choice: warping on time x frequency domain

- discrete transform: lapped cosine (LCT).
- frequency contents are not deformed ⇒ "texture" of the movement is preserved.
- cycles are detected by using an autocorrelation method.

Time x Frequency Decomposition of 1D Signals

Temporal decomposition into frequency packets
– cosine transform.

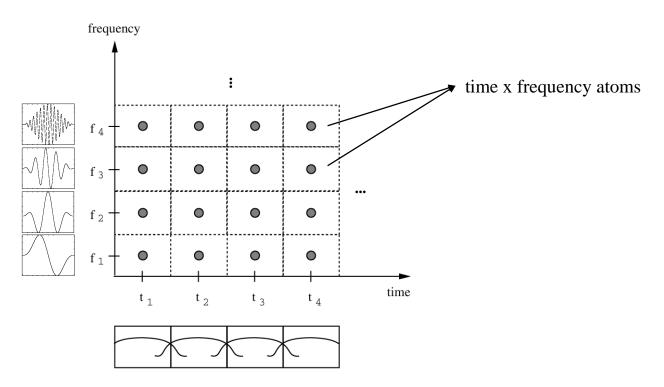


- Lapped cosine transform (LCT)
 - orthonormal basis.
 - window overlapping ⇒ reduces boundary discontinuity.

Time x Frequency Representation of 1D Signals

• Finite partition of the time x frequency plane

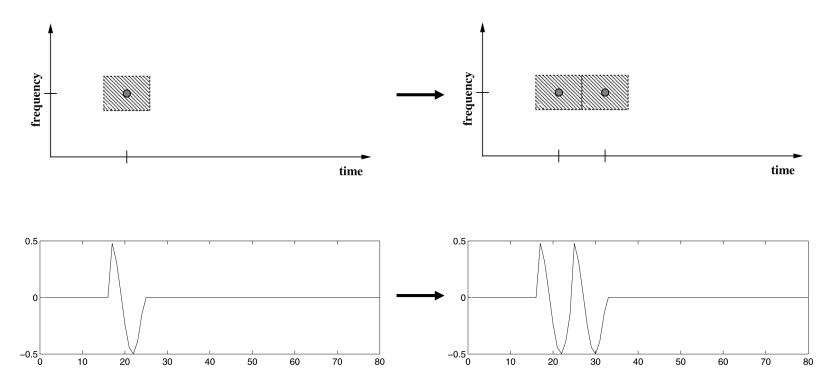
- vertical axis: frequency elements of the LCT basis.
- horizontal axis: overlapped time windows.



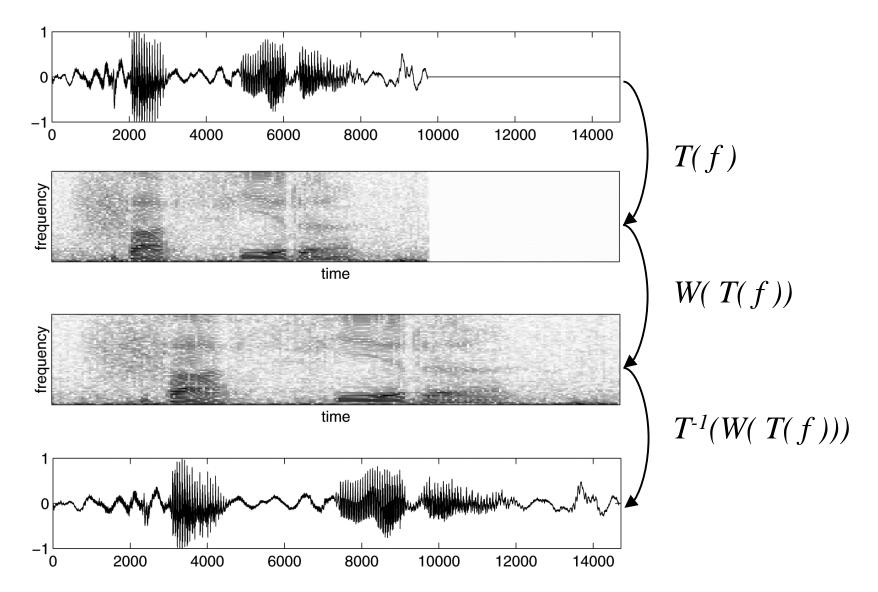
Time x Frequency Dilation of 1D Signals

• Affine dilation on the time axis

replication of atom elements of the time x frequency representation.



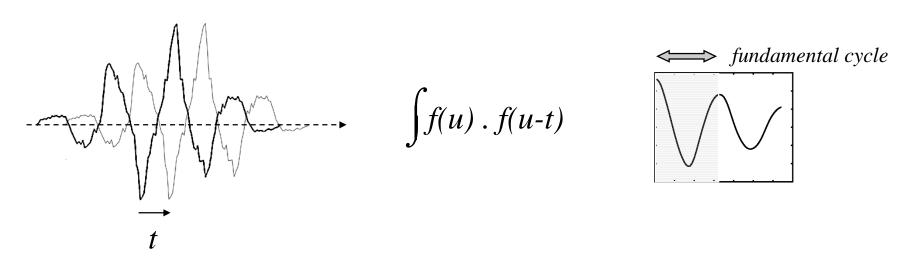
Time x Frequency Warping of 1D Signals



Automatic Cycle Detection

• Fundamental cycle (FC)

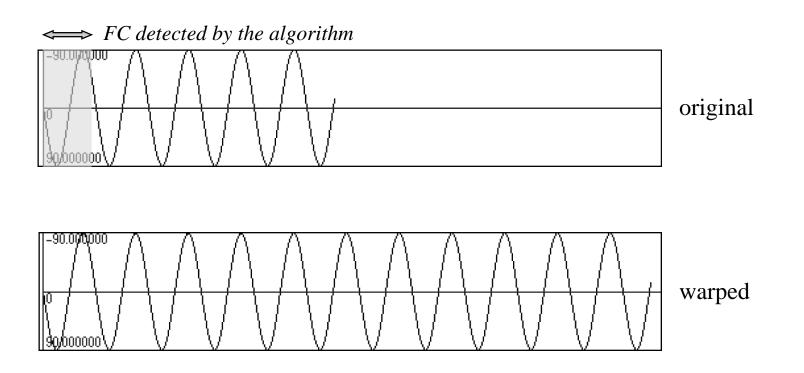
- circular autocorrelation method: measures the similarity between translated versions of a signal.
- FC is given by the distance between consecutive maximum points.
- lowest frequency in the signal.



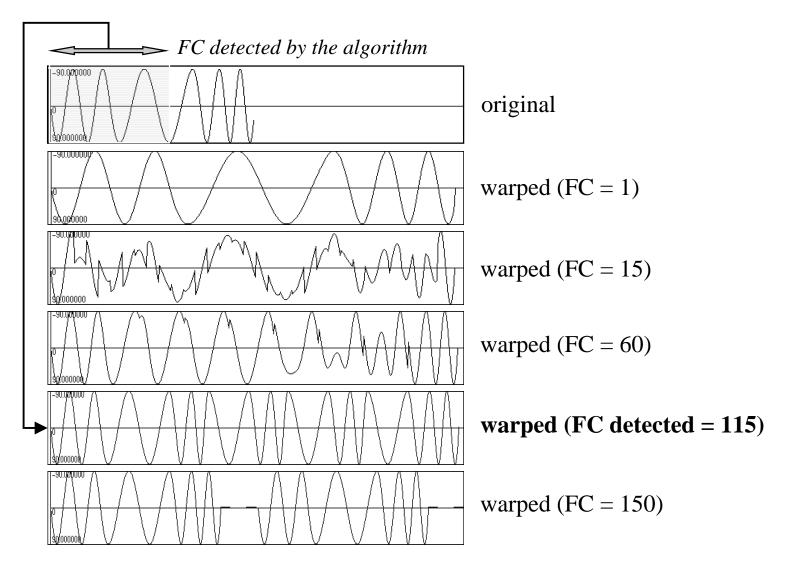
Experiments (1 DOF)

- Re-timing with warp factor = 2.0
- Tests with sinusoidal functions
 - sine with fixed period.
 - *sine* with variable period and window size.
- Kinematic simulation of a pendulum
- Left upper arm joint motion curve

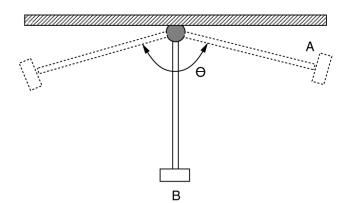
- *sine* function with fixed period.

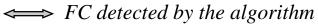


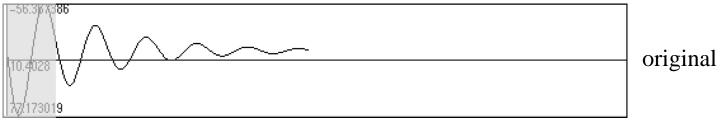
- *sine* function with variable period and FC.

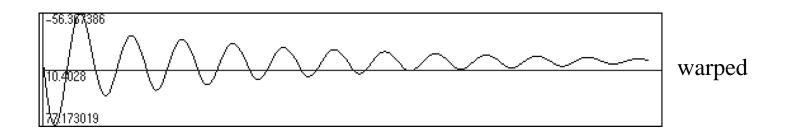


 kinematic simulation of a pendulum.

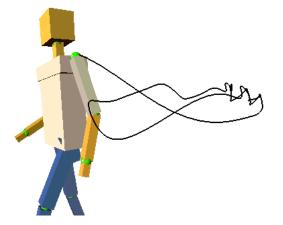




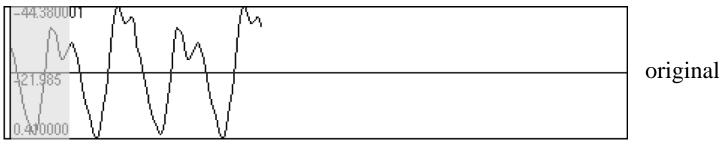


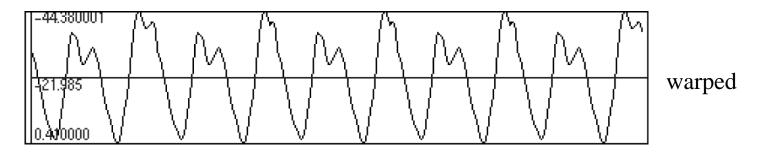


left upper arm joint motion curve.



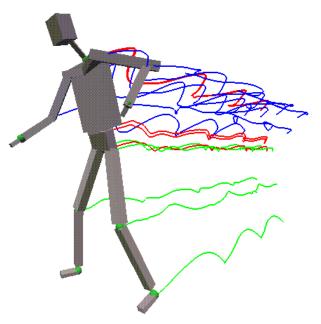
 \iff FC detected by the algorithm





Cyclification of Articulated Figure Motion

- Articulated figure: complex structure
 - multiple joints and DOFs.
 - large amount of data to process and control.
 - *near-periodic* motions: synchronism between joints must be preserved by the warping algorithm.



Strong and Weak Phase Dependence

• Strong

- direct structural relationship between joints (e.g. motion of knee and foot is influenced by upper leg joint motion).
- common periodic behavior ⇒ phases are multiples of a predominant FC.

• Weak

- indirect structural relationship between joints (e.g. motion of arms and legs).
- happens due to balance and stability control.

Strong and Weak Phase Dependence

• Walk sequence

- strong dependence between outer and inner joints in arms and legs.
- weak dependence between arms and legs (cross synchronization).

 $\begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 10 \\ 1 \end{bmatrix} \begin{bmatrix} 20 \\ 1 \end{bmatrix} \begin{bmatrix} 25 \\ 1 \end{bmatrix} \begin{bmatrix} 30 \\ 1 \end{bmatrix} \begin{bmatrix} 35 \\ 1 \end{bmatrix} \begin{bmatrix} 40 \\ 1 \end{bmatrix} \begin{bmatrix} 45 \\ 1 \end{bmatrix} \begin{bmatrix} 50 \\ 1 \end{bmatrix} \begin{bmatrix} 55 \\ 1 \end{bmatrix}$

• Backflip kick sequence

- strong dependence between outer and inner joints in arms and legs.
- weak dependence between arms and legs (coupled synchronization).



Detection of Predominant Cycle

• For each group of joints

- apply autocorrelation method to all motion curves, generating a set of FCs.
- take the greater FC.
- warp all motion curves within joint group using as input the selected FC.

Conclusions

• New technique for cyclification of motion curves

- time x frequency warping algorithm.
- preserves the *shape* and *texture* of the curves.
- works well with periodic and *near-periodic* curves.
- Cyclification of articulated figure motion
 - analysis of strong and weak dependencies between body segments.
- Video with results

Future Work

- Algorithm extension and improvement
 - complex human figure motion.
- Synchronization of facial animation and audio
 - non-linear audio editing.
 - film dubbing (lip-sync).
- Integration of method on a full animation system
 - transform simultaneously human motion, facial animation and sound.

Additional Info

http://www.visgraf.impa.br/mocap

- *sine* function with variable period and noise.

